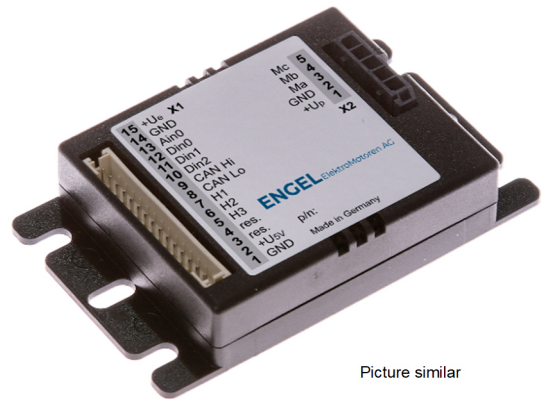


Drive Controller EDC-B60

Absolute maximum rating (destruction limits)	
Power supply voltage U_p no polarity reversal protection	80 V
Continuous Electronic supply voltage U_e no polarity reversal protection	33 V
Short term peak voltage < 1s U_e no polarity reversal protection	37 V
Power	
Electronic supply voltage U_e	9..30 V
Electronic current consumption @ $U_e=24V^{*1}$	typ. 20 mA
Power supply voltage U_p	9..60 V
Max. output current	15 A
Continuous output current @ $U_p=24V^{*2}$	5 A
Continuous output current @ $U_p=48V^{*2}$	4.3 A
PWM	
Output voltage	90% U_p
PWM frequency	12.5, 25 ^{*3} kHz
Mechanical	
Size LxWxH	74 x 45 x 17 mm
Weight	30 g
Environment	
Protection class	IP20
Ambient temperature (operation)	-25..70 °C
Ambient temperature (storage)	-25..85 °C
Rel. humidity (non-condensing)	5..90 %
CAN bus	
Protocol	DS301
Max. baudrate	1 Mbit/s
CAN specification	2.0B
Galvanically isolated	no

Sensor supply (Hall)	
Output voltage	5 V
Max. output current	0.2 A
Hall sensors	
Signals	H1,H2,H3
Max. frequency (per channel)	10 kHz
Input voltage	0..5 V
Signal type	open collector, single ended
Digital inputs	
Number - digital inputs	3 (Din0..2)
Low voltage	0..5 V
High voltage	8..30 V
Analog inputs	
Number	1 (Ain0)
Signal type	0..10 V, 12 Bit, single ended



Picture similar

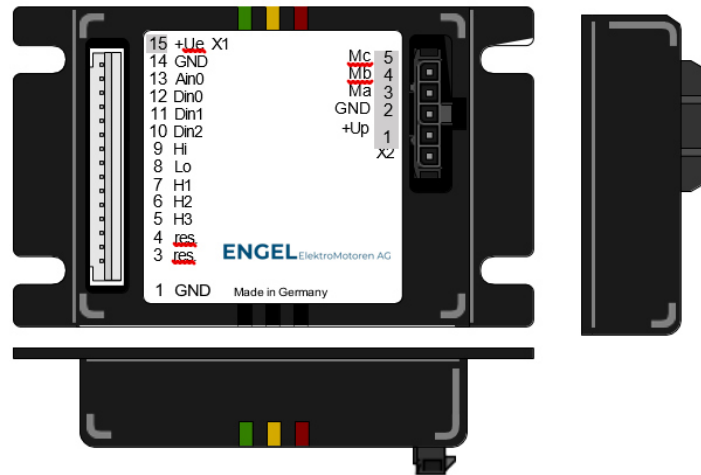
^{*1} drive controller switched off, 5V output (sensor supply) is free

^{*2} connector cable with max. possible cable cross-section, PWM frequency 25 kHz, ambient temperature 40 °C (t >40 °C derating), RMS current: 5 A → 4.1 Aeff, 4.3 A → 3.5 Aeff, no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

^{*3} default value

Additional technical data are available in [edcManual](#).

Scheme



Terminal assignment

X1	Hall, I/O's and CAN	
1	GND	Ground for sensor supply Notice: don't connect with system GND
2	+U5V	5V output voltage for sensor supply Sensors: hall
3	res.	Reserved
4	res.	Reserved
5	H3	Hall sensor 3
6	H2	Hall sensor 2
7	H1	Hall sensor 1
8	CAN Lo	CAN Low
9	CAN Hi	CAN High
10	Din2	Digital input 2
11	Din1	Digital input 1
12	Din0	Digital input 0
13	Ain0	Analog input 0
14	GND	Ground for electronic supply voltage
15	+Ue	Electronic supply voltage
X2	Motor	
1	+Up	Power supply voltage
2	GND	Ground for power supply voltage
3	Ma	Motor phase A
4	Mb	Motor phase B
5	Mc	Motor phase C