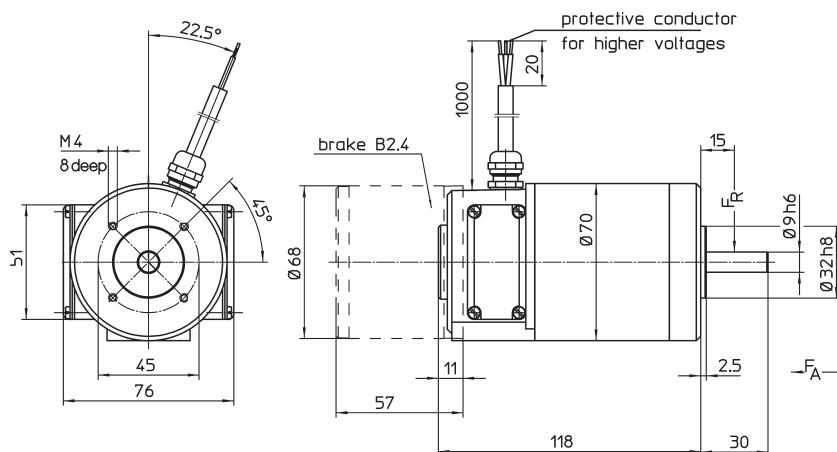


GNM 4125

**DC
Motors**
with permanent magnet field

Motor series GNM 4125
up to 60 Watts output power
with + without parking brake

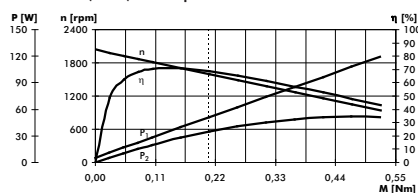


Operation characteristics:

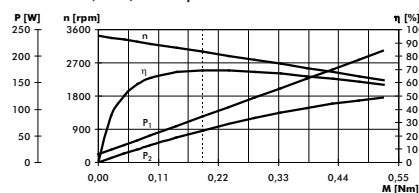
n - Speed
 η - Efficiency

P_1 - Input power
 P_2 - Output power

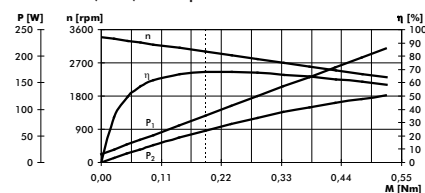
GNM4125, 24V, 1600rpm



GNM4125, 24V, 3000rpm



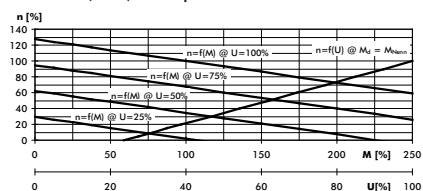
GNM4125, 42V, 3000rpm



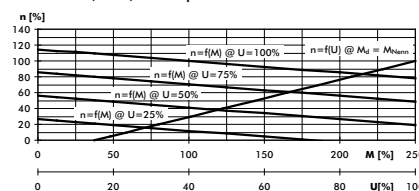
Control characteristics :

n=f(M) - Speed as a torque function
n=f(U) - Speed as a supply voltage function

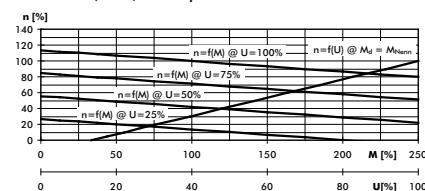
GNM4125, 24V, 1600rpm



GNM4125, 24V, 3000rpm



GNM4125, 42V, 3000rpm



		GNM 4125		
type series	rpm	1 600	3 000	3 000
nominal speed	V	24	24	42
nominal voltage	A	2,15	3,6	2,1
nominal current	W	35	60	60
nominal power			S1	
operation acc. to VDE 0530			IP 54	
protection acc. to VDE 0530			light plastic-sheathed cable	
connection			reversible	
rotating direction			IMB 14	
design				
mechanical data:				
mass moment of inertia	kgm ²	0,209	0,191	0,0558*10 ⁻³
nominal torque	Nm	0,87	1,35	0,191
starting torque	Nm	0,23	0,23	1,35
max. continuous torque at stall	Nm	21	23	0,23
speed regulation constant	N ⁻¹ cm ⁻¹ rpm	12,3	13,5	21
mechanical time constant	ms	0,025	0,04	12,3
friction torque	Nm			0,04
rotor weight	kg		0,425	
motor weight	kg		1,45	
motor weight incl. parking brake	kg		1,85	
ball bearings			629/629	
F _r (allowable radial shaft load)			130	
F _A (allowable axial shaft load)			52	
electrical data:				
armature resistance	Ω	2,52	0,86	2,52
armature inductance	mH	5,8	1,85	5,8
terminal resistance	Ω	2,66	1	2,66
voltage constant	V/1000 rpm	11,47	6,73	11,47
torque constant	Nm/A	0,11	0,0643	0,11
starting current	A	9	24	15
max. peak current ¹⁾	A	14	24	14
electrical time constant	ms	2,2	1,85	2,2
thermal data:				
max. ambient temperature	°C		40	
insulation class acc. to VDE 0530			F	
thermal time constant	min		40	
temperature-rise without cooling	K/W	6,1	3,95	3,95
parking brake B 2:				
nominal voltage	V		24	
nominal current	A		0,35	
static break torque (motor shaft)	Nm		0,8	
max. number of operations per hour			2000	
Tolerances acc. to standard VDE 0530. ± 10 % is valid for not VDE mentioned tolerances.				
The values mentioned in the table are valid for supply with DC voltage with allowable harmonic content up to 5%. For undulatory current with increased harmonic content the rated motor values must be multiplied by 0,7.				
¹⁾ The values are valid for operation in temperature-ranges from 0 up to 40°C and it is not allowed to exceed them, even not for a short-time, to avoid magnet-weakening.				
<ul style="list-style-type: none"> ● Motors also available with DC tachogenerator and/or incremental encoder. ● Motors also available with device plug DIN 43650. 				
		Motor design: Brushed 2-pole DC motor with permanent magnet field. Brush holder opening will be accessible by removing the cover plate. Flange mounting with 4 threads (see drawing).		
		Rotating direction: The rotating direction can be changed by inverting the connections.		
		<ol style="list-style-type: none"> 1. Order example Motor GNM 4125A 24 V, 1 600 rpm, 35 W Special designs on request. 2. Order example Motor GNM 4125A 42 V, 3 000 rpm, 60 W - DC tachogenerator - T 17.05 - 5 V / 1 000 rpm 		